

**ABSTRACT:**

Please amend the current Abstract and enter the following new Abstract.

**Marked-up version****ABSTRACT**

A method of locating difficult access points~~The locating of difficult access points,~~  
on a topological map includes: ~~of the zone overflowed by an aircraft, plotted on the basis~~  
~~of a map of curvilinear distances taking account of the vertical flight profile of the~~  
~~aircraft, is effected by analyzing the map of curvilinear distances, by means of using a~~  
chamfer mask to catalogue ~~cataloging the approximate values  $C(V)$  of the Euclidean~~  
distances separating a point  $C_{00}$  of the map from its nearest neighbors  $V_i$ , ~~so as to~~  
~~extract; determining~~ therefrom, at each point  $C_{00}$  of the map of curvilinear distances, the  
discrepancies  $|DT(V)-DT(0)|$   ~~$(DT(V)-DT(0))$~~  of curvilinear distances separating the point  
considered  $C_{00}$  from its nearest neighbors  $V_i$ , ~~compare;~~ comparing these discrepancies  
 ~~$(DT(V)-DT(0))$  with the approximate values  $C(V)$ ; and determining of the Euclidean~~  
~~distances of the chamfer mask and describe the point considered as a difficult of~~  
~~access~~ access point ~~when a difference is noted~~ based upon a difference between the  
Euclidean distance and the determined discrepancies ~~discrepancy~~ of curvilinear  
distances. ~~This locating proves to be useful for signaling the reliefs that are not~~  
~~accessible by a shortest path but are accessible after detour.~~

**Clean version****ABSTRACT**

A method of locating difficult access points on a topological map includes: analyzing curvilinear distances using a chamfer mask to catalogue approximate values  $C(V)$  of the Euclidean distances separating a point  $C_{00}$  of the map from its nearest neighbors  $V$ ; determining therefrom, at each point  $C_{00}$  of the map of curvilinear distances, the discrepancies  $|DT(V)-DT(0)|$  of curvilinear distances separating the point considered  $C_{00}$  from its nearest neighbors  $V$ ; comparing these discrepancies with the approximate values  $C(V)$ ; and determining the point as a difficult access point based upon a difference between the Euclidean distance and the determined discrepancies of curvilinear distances.